

# *SEE 3243/4243*

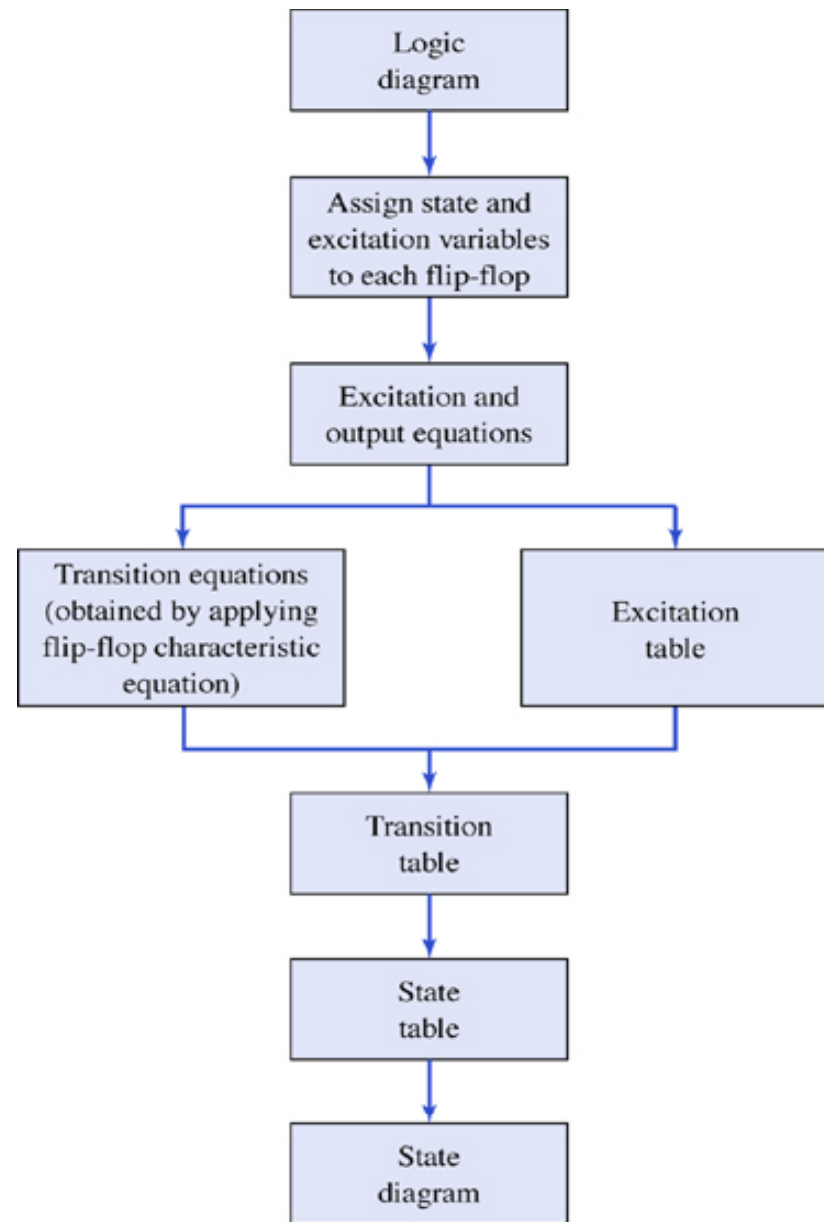
## *FSM Analysis*

Week 11

- Getting state diagram from a circuit
  - Moore examples
  - Mealy examples

## Analysis procedure

- Two techniques for reverse engineering:
  - **Ad Hoc:** Try input combinations to derive transition table
    - Try avoiding ad hoc method
  - **Formal:** Derive transition by analyzing the circuit

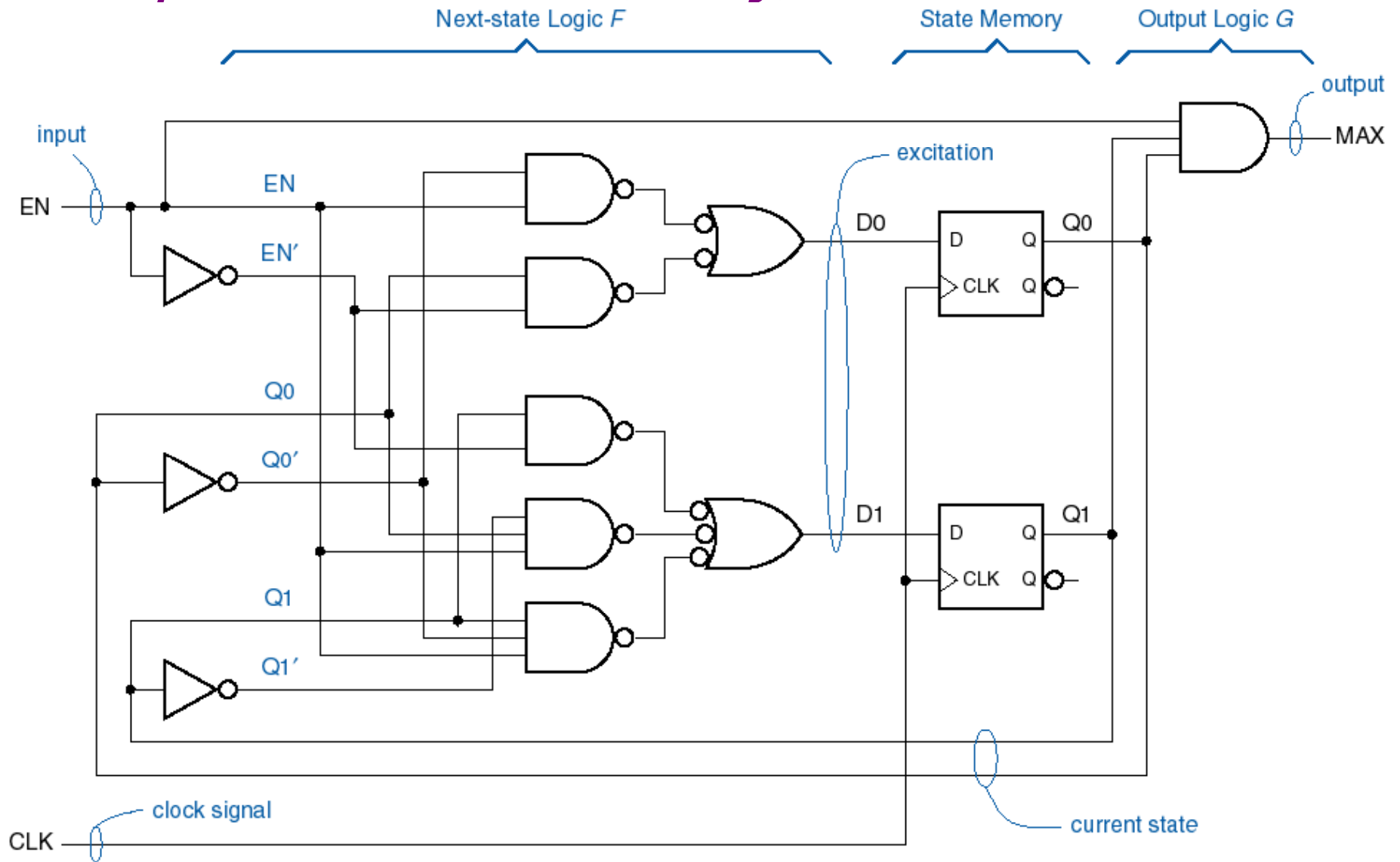




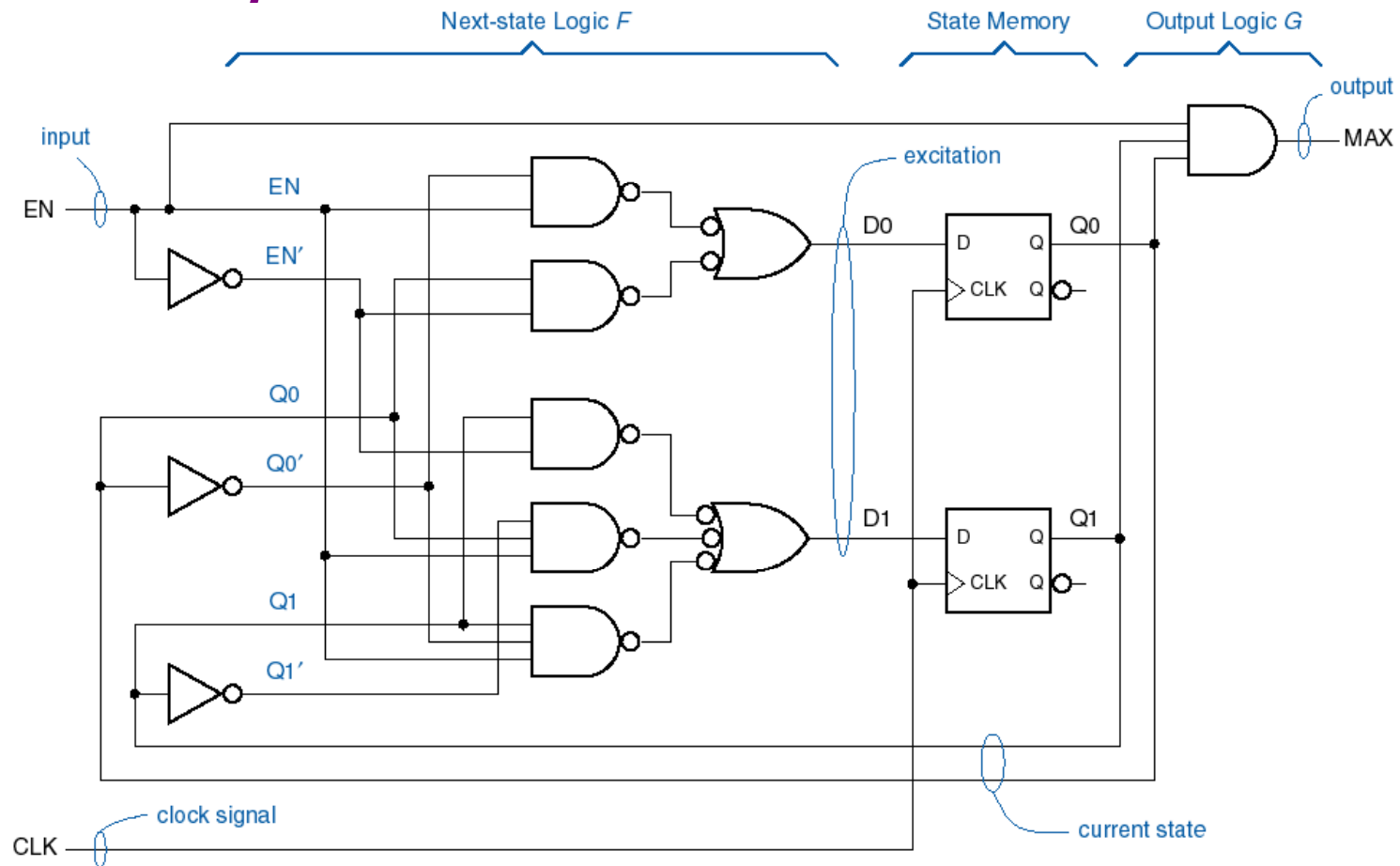
## *State-machine analysis steps*

- Assumption: Starting point is a logic diagram.
  1. Determine next-state function  $F$  and output function  $G$ .
  - 2a. Construct state table
    - For each state/input combination, determine the excitation value.
    - Using the characteristic equation, determine the corresponding next-state values (trivial with DFFs).
  - 2b. Construct output table
    - For each state/input combination, determine the output value. (Can be combined with state table.)
  3. (Optional) Draw state diagram

# Example state machine (Mealy)



# Excitation equations



$$D0 = Q0 \cdot EN' + Q0' \cdot EN$$

$$D1 = Q1 \cdot EN' + Q1' \cdot Q0 \cdot EN + Q1' \cdot Q0' \cdot EN$$

## *Transition equations*

- Excitation equations

$$D_0 = Q_0 \cdot EN' + Q_0' \cdot EN$$

$$D_1 = Q_1 \cdot EN' + Q_1' \cdot Q_0 \cdot EN + Q_1 \cdot Q_0' \cdot EN$$

- Characteristic equations (Trivial for DFF!)

$$Q_0^+ = D_0$$

$$Q_1^+ = D_1$$

- Substitute excitation equations into characteristic equations

$$Q_0^+ = Q_0 \cdot EN' + Q_0' \cdot EN$$

$$Q_1^+ = Q_1 \cdot EN' + Q_1' \cdot Q_0 \cdot EN + Q_1 \cdot Q_0' \cdot EN$$

## Transition and state tables

$$Q0^* = Q0 \cdot EN' + Q0' \cdot EN$$

$$Q1^* = Q1 \cdot EN' + Q1' \cdot Q0 \cdot EN + Q1 \cdot Q0' \cdot EN$$

$$MAX = Q1 \cdot Q0 \cdot EN \text{ (output equation)}$$

(transition equations)

<b>Q1 Q0</b>	<b>EN</b>	
	<b>0</b>	<b>1</b>
00	00	01
01	01	10
10	10	11
11	11	00

**Q1\* Q0\***

transition table

<b>S</b>	<b>EN</b>	
	<b>0</b>	<b>1</b>
A	A	B
B	B	C
C	C	D
D	D	A

**S\***

state table

<b>S</b>	<b>EN</b>	
	<b>0</b>	<b>1</b>
A	A, 0	B, 0
B	B, 0	C, 0
C	C, 0	D, 0
D	D, 0	A, 1

**S\*, MAX**

state/output table

# Transition and state tables (using K-map)

$$Q0^* = Q0 \cdot EN' + Q0' \cdot EN$$

$$Q1^* = Q1 \cdot EN' + Q1' \cdot Q0 \cdot EN + Q1 \cdot Q0' \cdot EN$$

$$MAX = Q1 \cdot Q0 \cdot EN \text{ (output equation)}$$

(transition equations)

Three K-maps for variables Q1, Q0, and MAX:

**Q1\*** K-map: Q1Q0 (00, 01, 11, 10) vs EN (0, 1). Values: (0,0)=0, (0,1)=0, (1,0)=1, (1,1)=1. A '0' is circled in the (1,0) cell.

**Q0\*** K-map: Q1Q0 (00, 01, 11, 10) vs EN (0, 1). Values: (0,0)=0, (0,1)=1, (1,0)=1, (1,1)=0. A '0' is circled in the (1,1) cell.

**MAX** K-map: Q1Q0 (00, 01, 11, 10) vs EN (0, 1). Values: (0,0)=0, (0,1)=0, (1,0)=0, (1,1)=0.

		EN	
Q1	Q0	0	1
00	00	00	01
01	01	01	10
10	10	10	11
11	11	11	00

Q1\* Q0\*

transition table

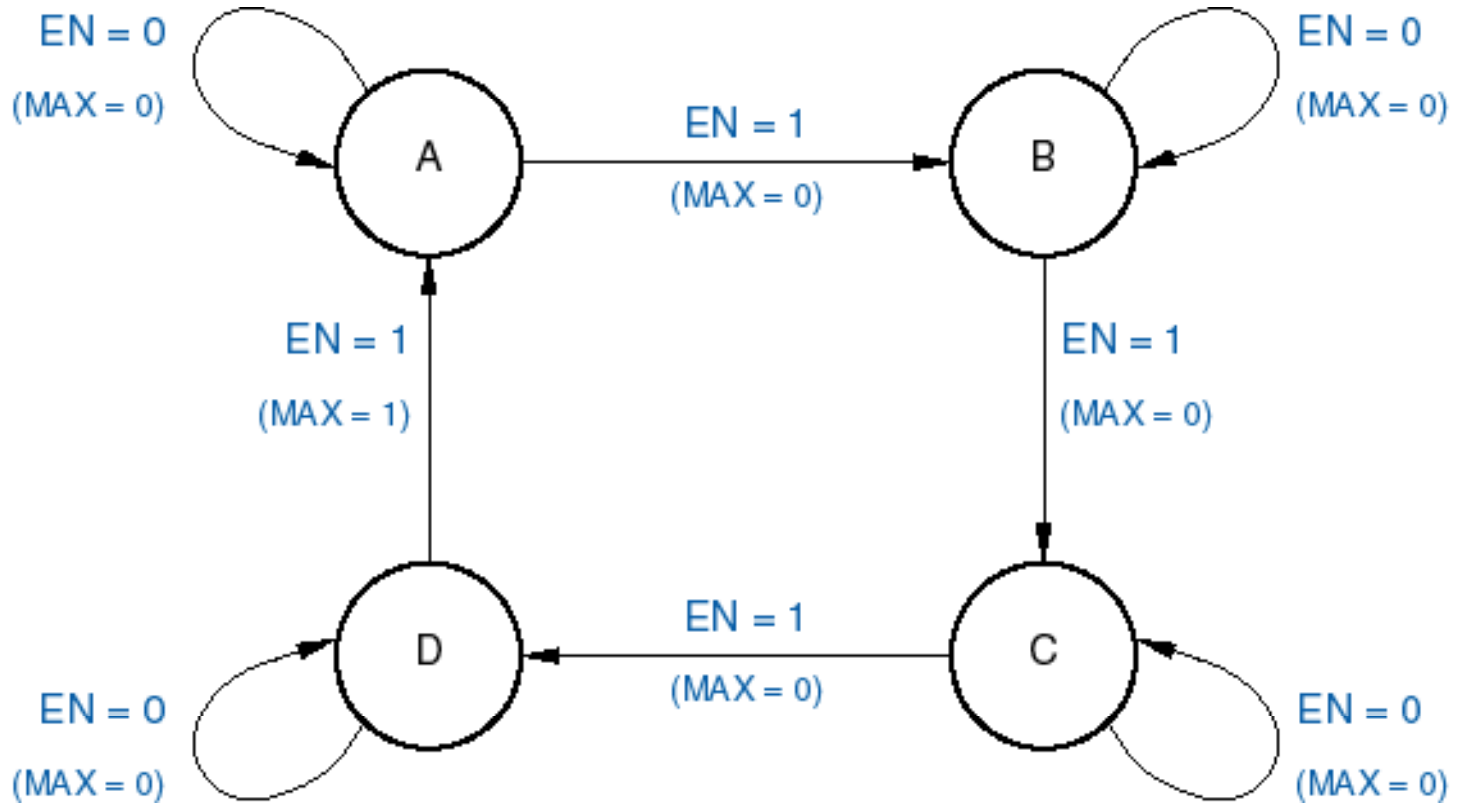
			EN	
S	0	1		
A	A, 0	B, 0		
B	B, 0	C, 0		
C	C, 0	D, 0		
D	D, 0	A, 1		

S\*, MAX

state/output table

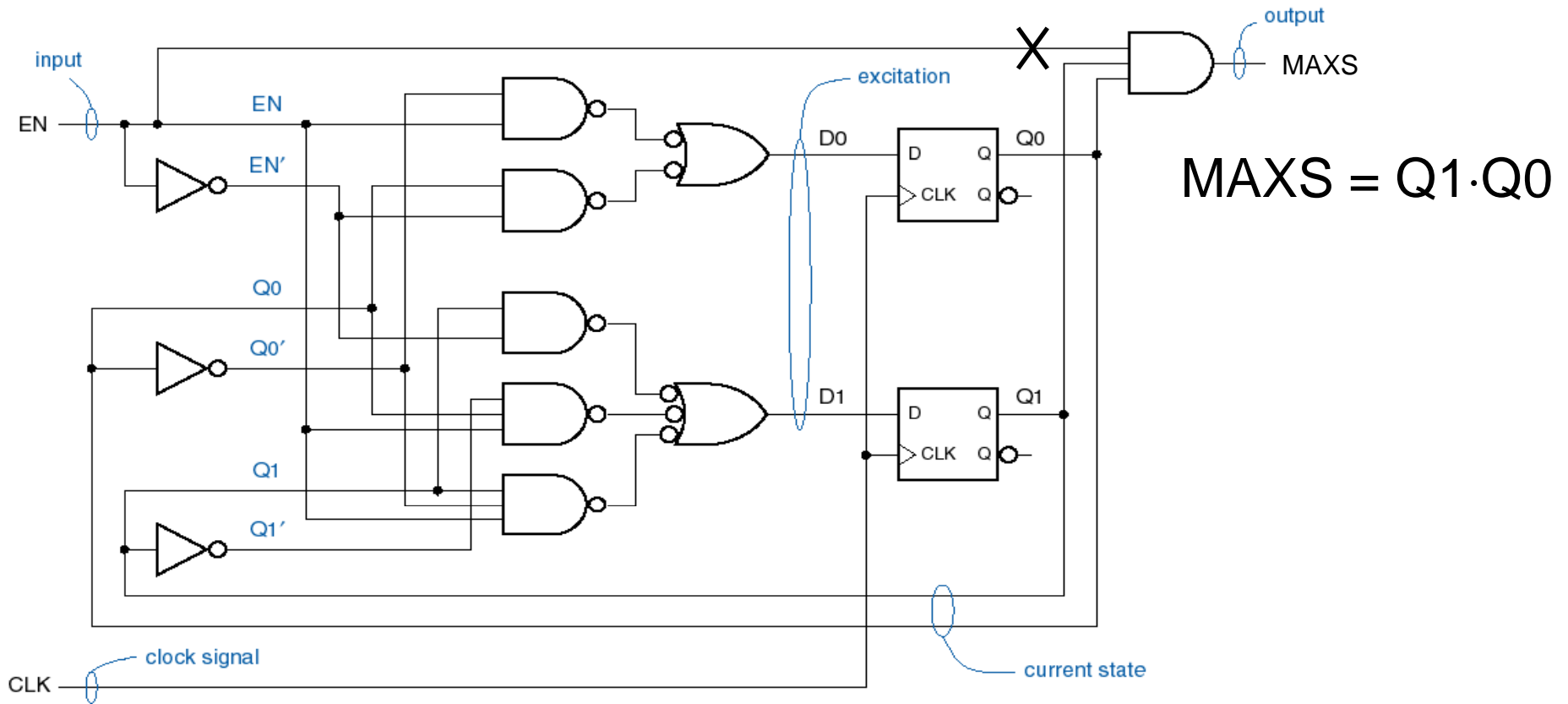


# State diagram



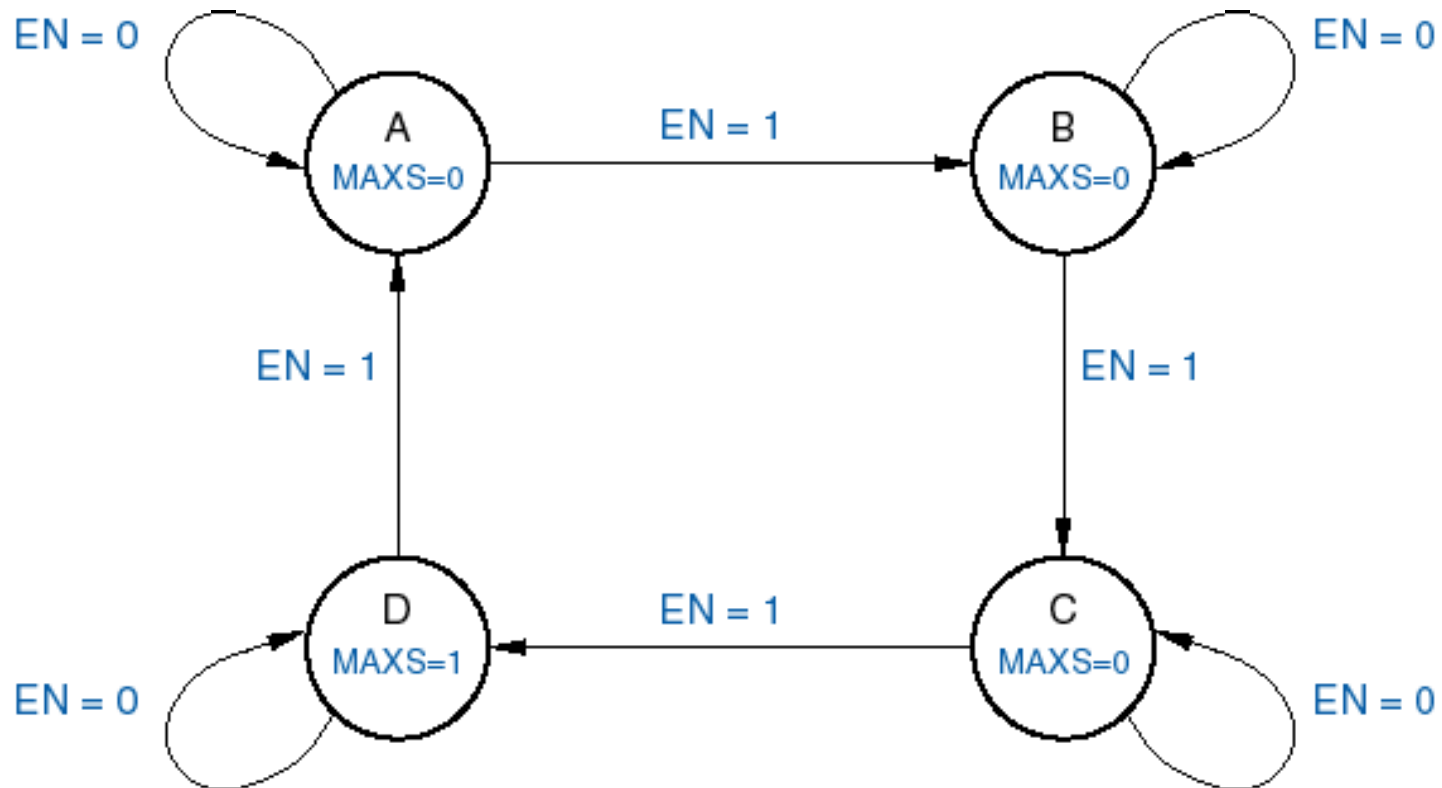
- Circles for states
- Arrows for transitions (note output info)

# Modified state machine (Moore machine)

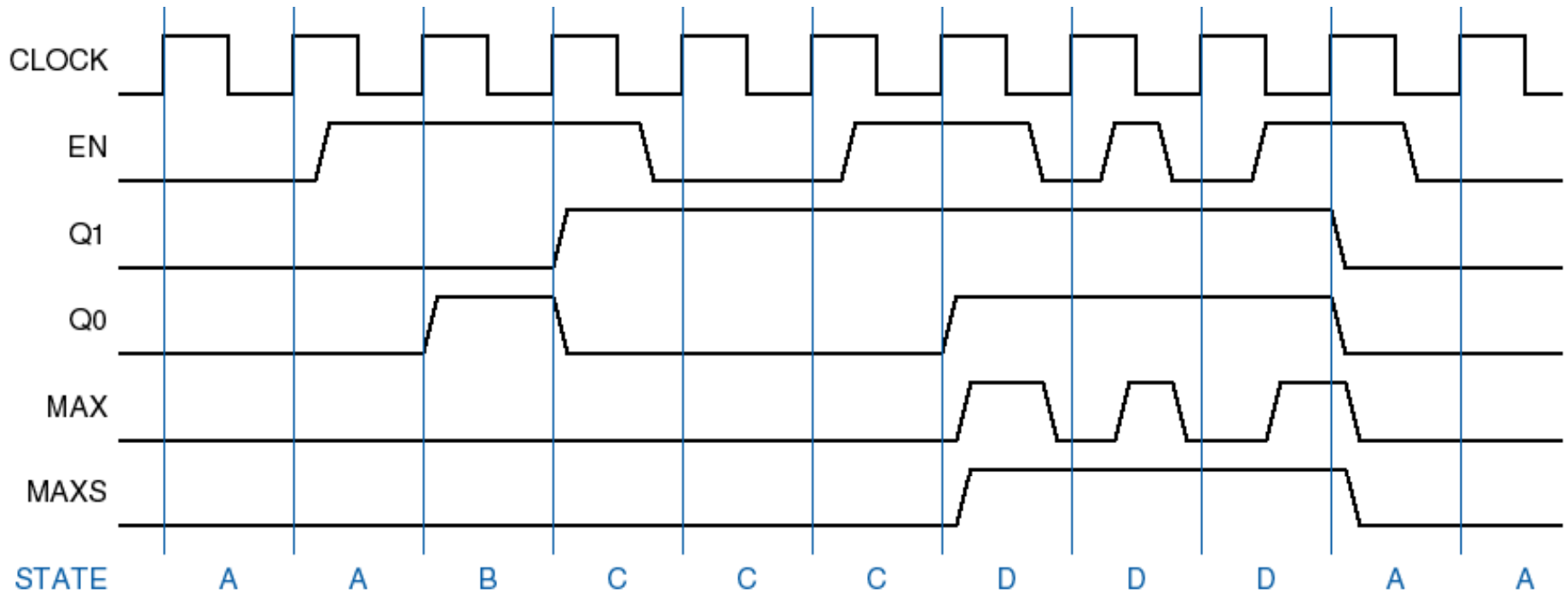


*Updated state/output table, state diagram*

S	EN		MAXS
	0	1	
A	A	B	0
B	B	C	0
C	C	D	0
D	D	A	1



## Timing diagram for state machine

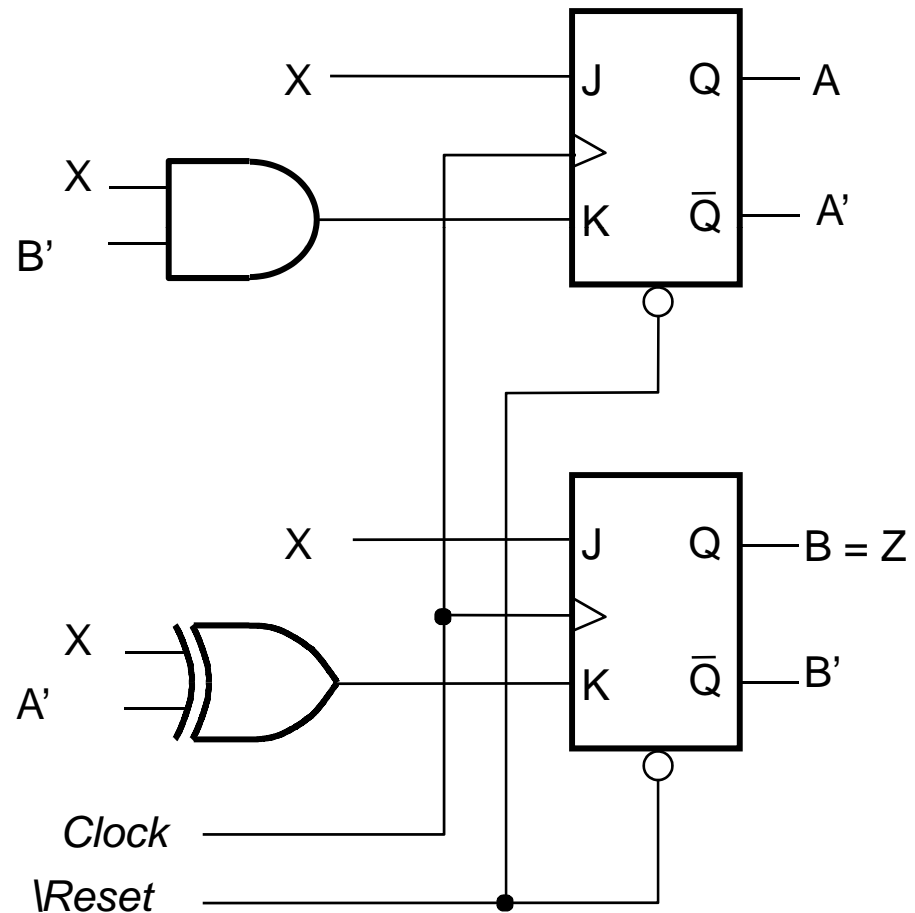


- **Not** a complete description of machine behavior. State diagram gives better description than timing diagram.

## Another example: analysis of Moore machine

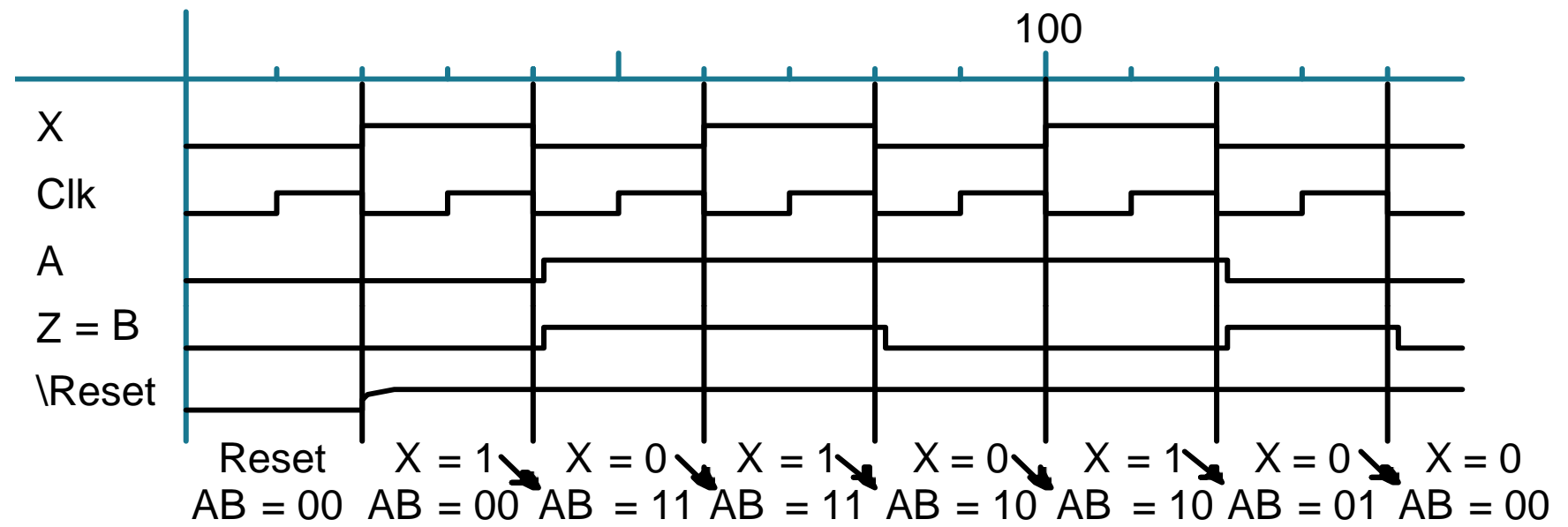
- Reverse engineer the following

Input X  
 Output Z  
 State A, B  
 ( $Z = B$ )



# Ad Hoc Reverse Engineering

Behavior in response to input sequence 1 0 1 0 1 0:



*Partially Derived State Transition Table*

A	B	X	A+	B+	Z
0	0	0	?	?	0
		1	1	1	0
0	1	0	0	0	1
		1	?	?	1
1	0	0	1	0	0
		1	0	1	0
1	1	0	1	1	1
		1	1	0	1

# Ad Hoc Reverse Engineering

*Partially Derived  
State Transition  
Table*

A	B	X	A+	B+	Z
0	0	0	?	?	0
		1	1	1	0
0	1	0	0	0	1
		1	?	?	1
1	0	0	1	0	0
		1	0	1	0
1	1	0	1	1	1
		1	1	0	1

We can complete the transition table by evaluating the circuit for the unknown conditions.  
For eg. when  $A = B = X = 0$ ,

$$J_a = K_a = 0, \text{ hence } A+ = 0$$

$$J_b = 0, K_b = 1, \text{ hence } B+ = 0$$

## Formal Reverse Engineering

- Derive transition table from next state and output combinational functions presented to the flipflops.

$$\begin{array}{lll} J_a = X & K_a = XB' & Z = B \\ J_b = X & K_b = X \oplus A' & \end{array}$$

- Characteristic equation for J-K FF

$$Q^+ = JQ' + K'Q$$

- FF excitation equations for J-K FF:

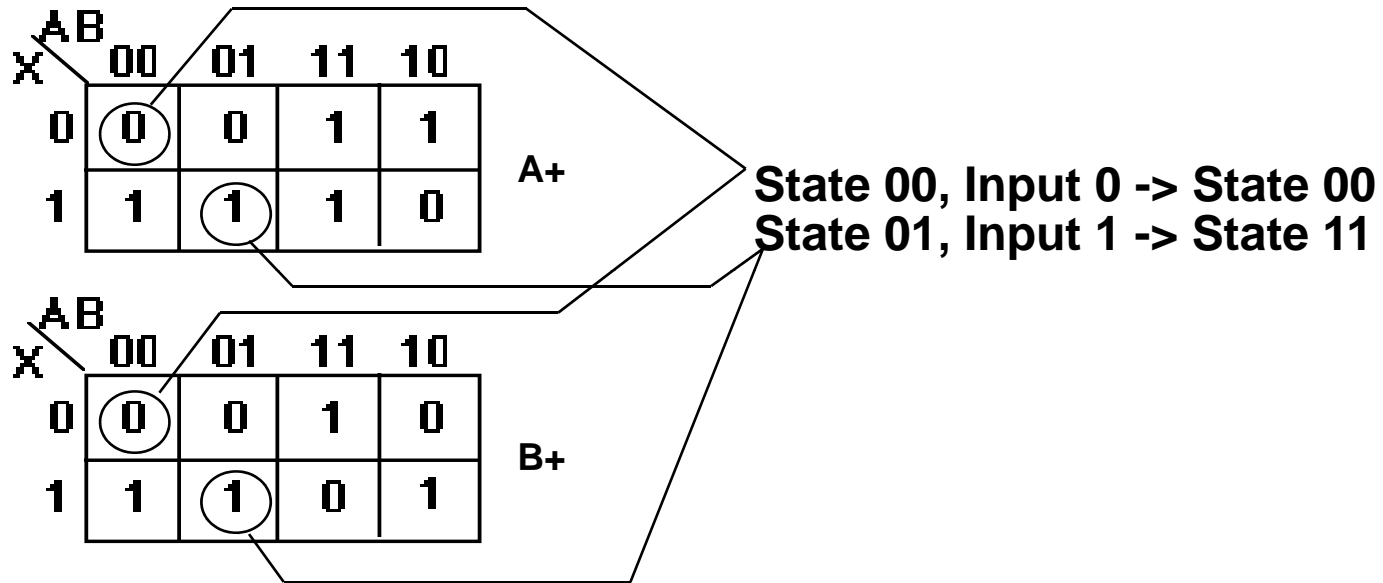
$$\begin{aligned} A^+ &= J_a A' + K_a' A \\ &= XA' + (XB')'A = XA' + (X' + B)A = A'X + AX' + AB \end{aligned}$$

$$\begin{aligned} B^+ &= J_b B' + K_b' B \\ &= XB' + (X \oplus A')'B \\ &= XB' + (X \text{ xnor } A')B = XB' + (AX' + A'X)B = B'X + ABX' + A'BX \end{aligned}$$



# Formal Reverse Engineering

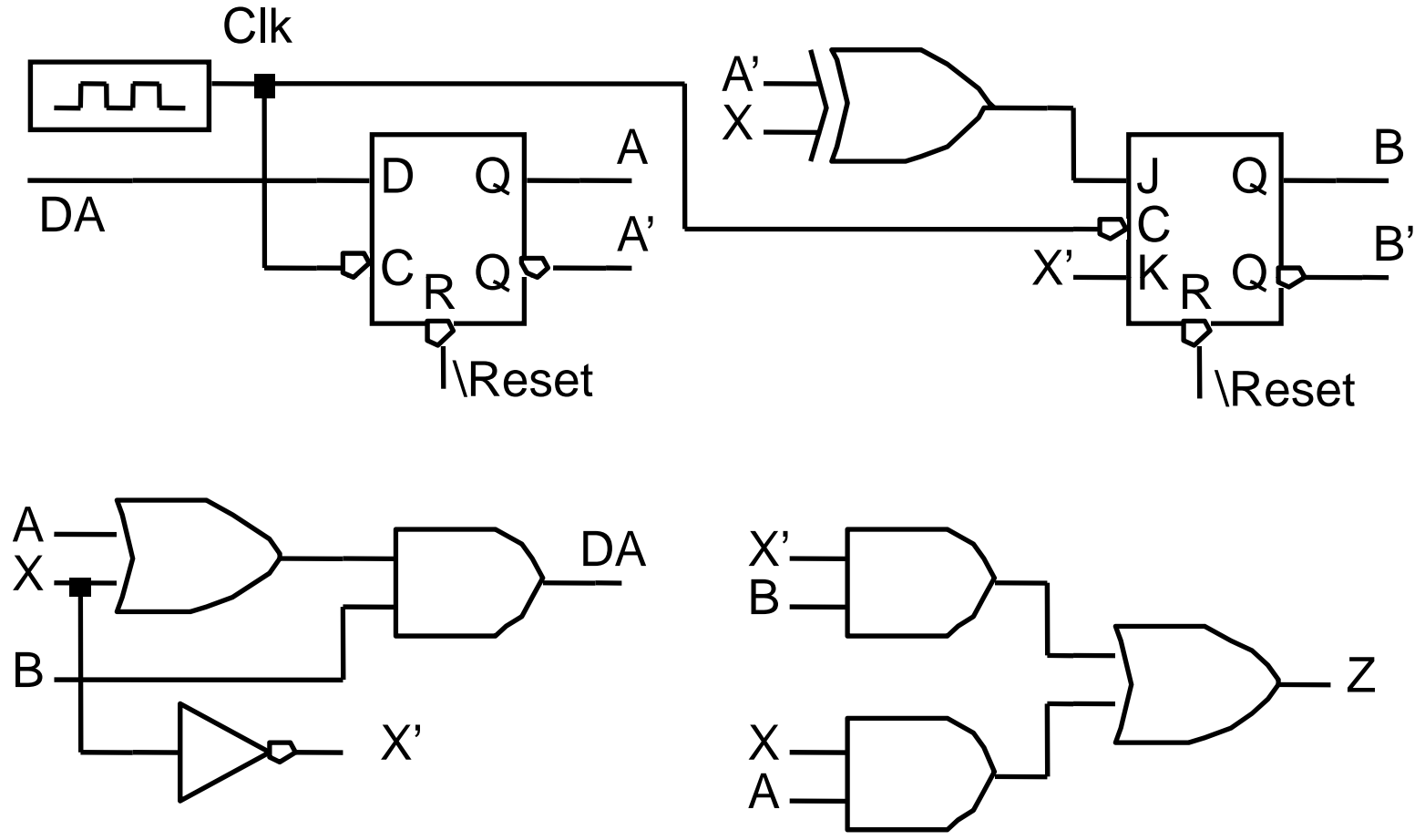
- Next state K-maps:



- Exercise: draw the state diagram.

## Another example: analysis of Mealy machine

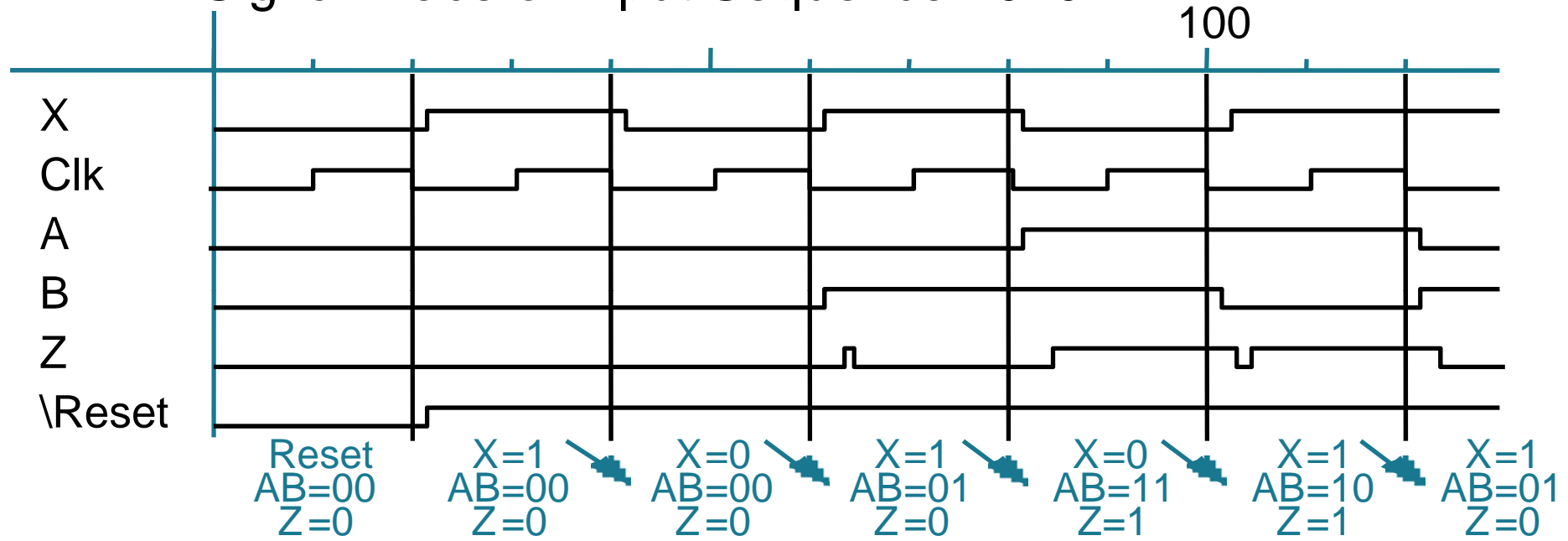
- Reverse engineer the following



Input X, Output Z, State A, B  
 State register consists of D FF and J-K FF

# Ad Hoc Reverse Engineering

Signal Trace of Input Sequence 101011:



*Partially completed state transition table based on the signal trace*

A	B	X	A+	B+	Z
0	0	0	0	1	0
0	1	0	?	?	?
0	1	1	1	1	0
1	0	0	?	?	?
1	0	1	0	1	1
1	1	0	1	0	1
1	1	1	?	?	?

## *Formal Reverse Engineering*

- Derive transition table from next state and output combinational functions presented to the flipflops.

$$\begin{array}{l}
 DA = (A + X)B \\
 J = AX + A'X' \qquad K = X' \qquad Z = BX' + AX
 \end{array}$$

- Characteristic equation for FF

$$Q^+ = D \qquad \text{(D FF)}$$

$$Q^+ = JQ' + K'Q \qquad \text{(J-K FF)}$$

- FF excitation equations:

$$A^+ = DA$$

$$= (A + X)B = AB + BX$$

$$B^+ = JB' + K'B$$

$$= (AX + A'X')B' + (X')'B$$

$$= AB'X + A'B'X' + BX$$

# Formal Reverse Engineering

- Next state K-maps:

		AB				
X		00	01	11	10	
0		0	0	1	0	
1		0	1	1	0	

A+

		AB				
X		00	01	11	10	
0		1	0	0	0	
1		0	1	1	1	

B+

		AB				
X		00	01	11	10	
0		0	1	1	0	
1		0	0	1	1	

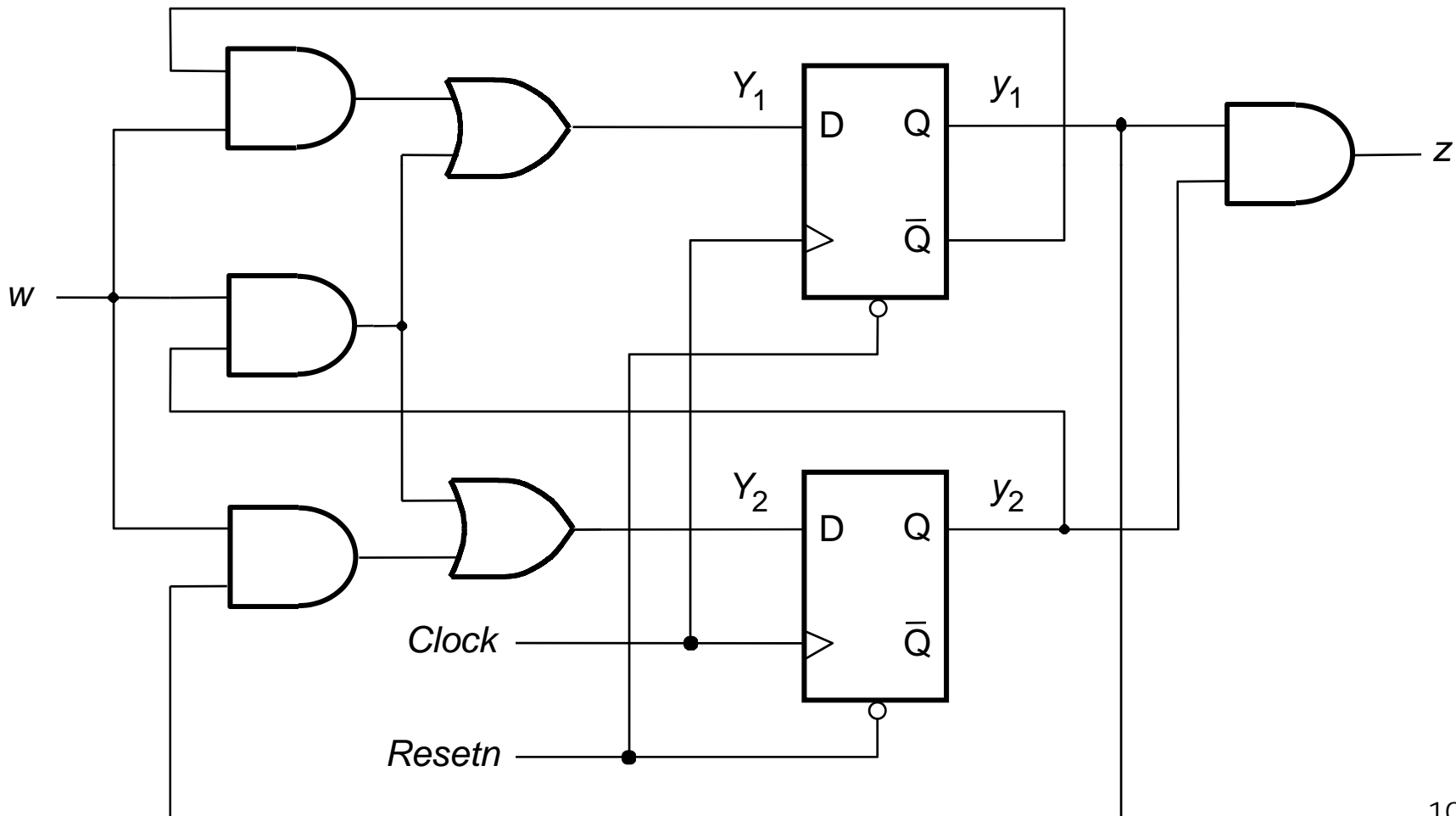
Z

State 11, Input 1 -> State 11, Output 1

- Exercise: draw the state diagram.

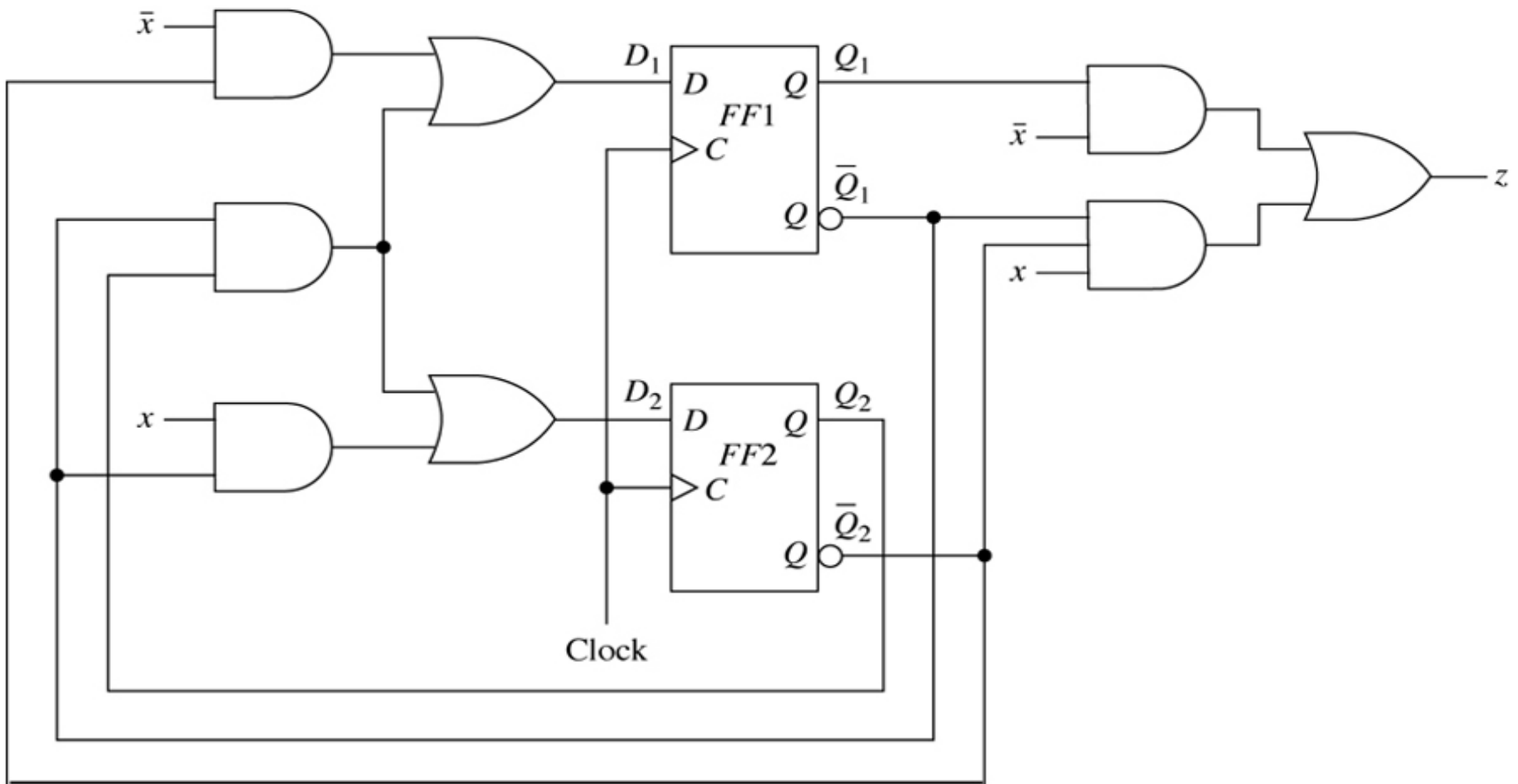
## Exercise 1

- Draw the state diagram for FSM below. The machine has one input  $w$  and one output  $z$ .



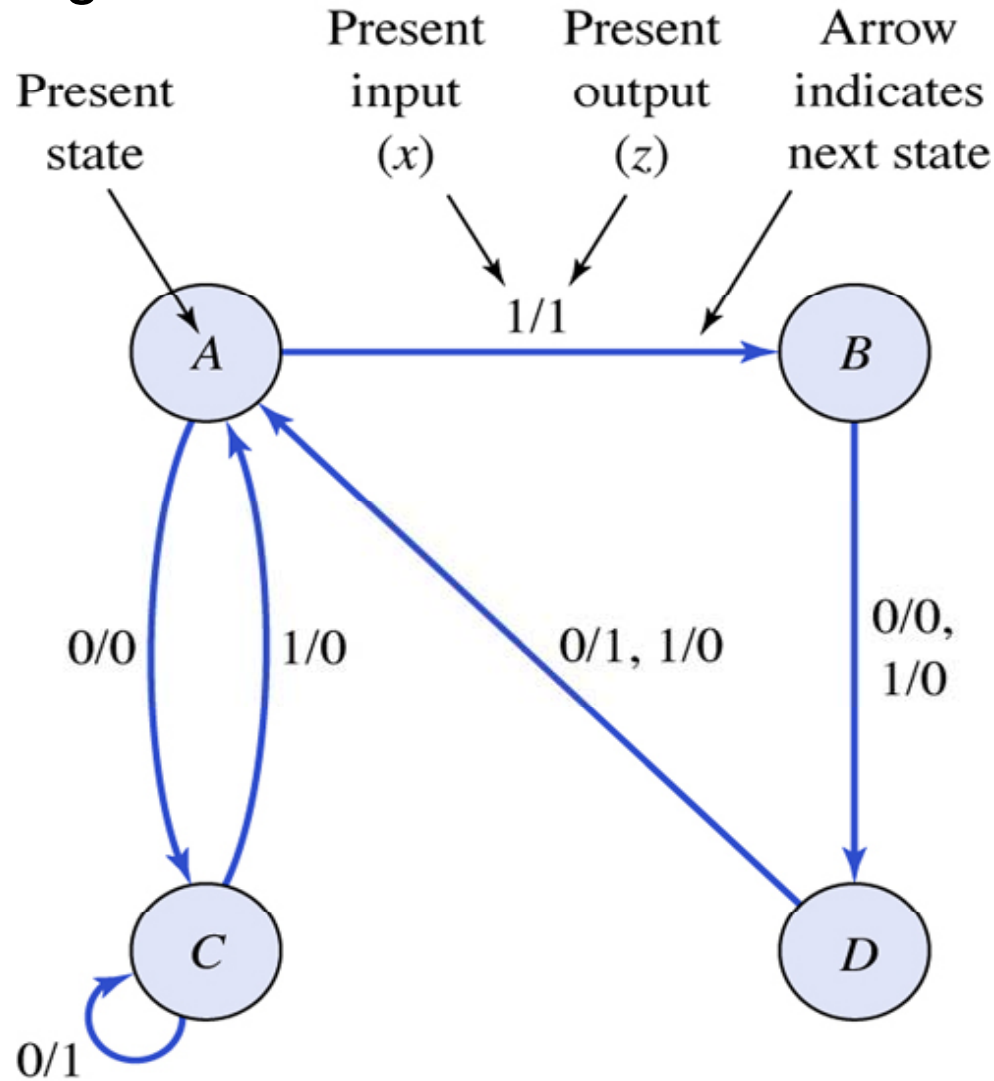
## Exercise 2

- Derive the state diagram for FSM below. The machine has one input  $x$  and one output  $z$ .



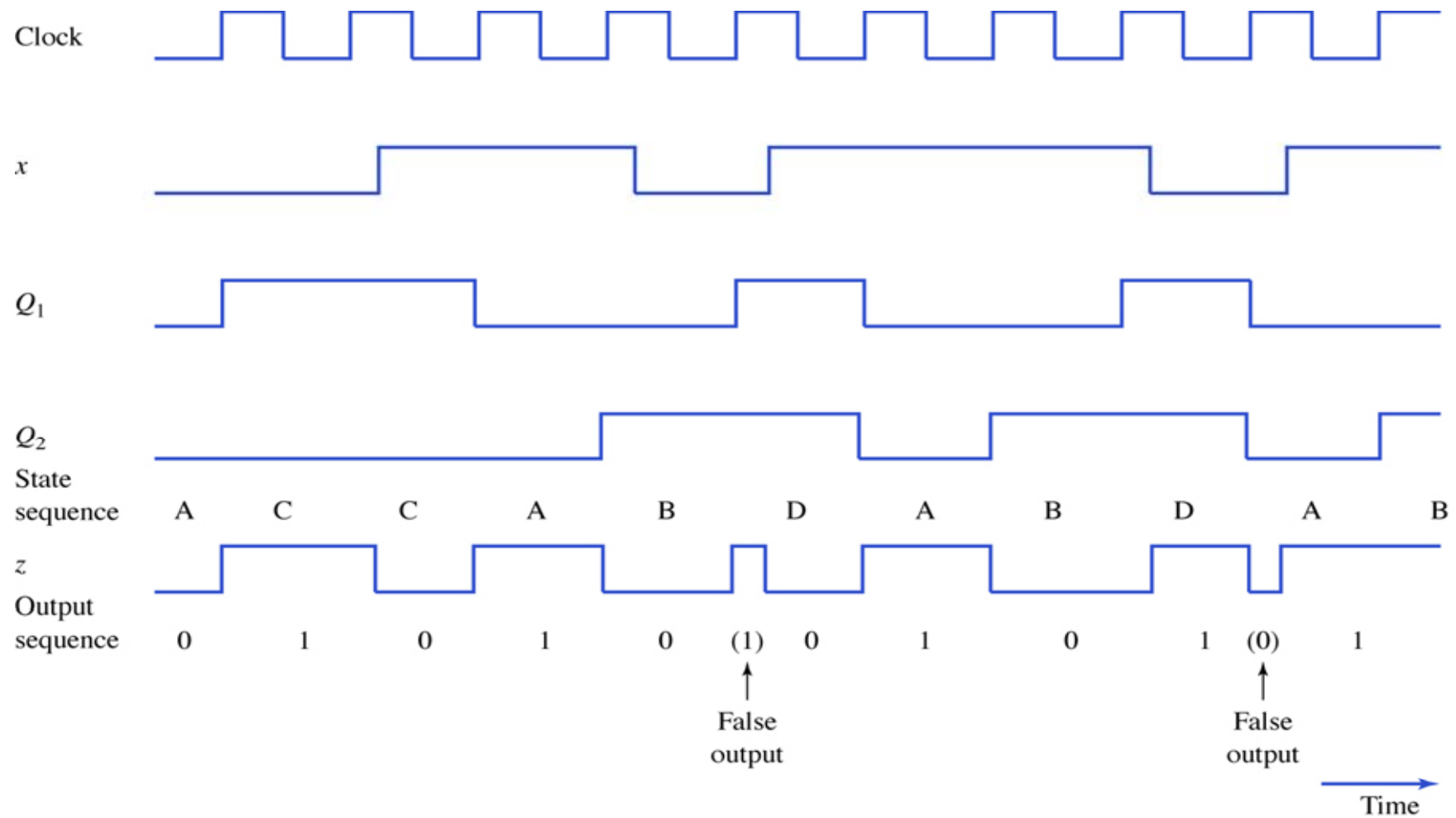
## Solution to Exercise 2

- The state diagram.



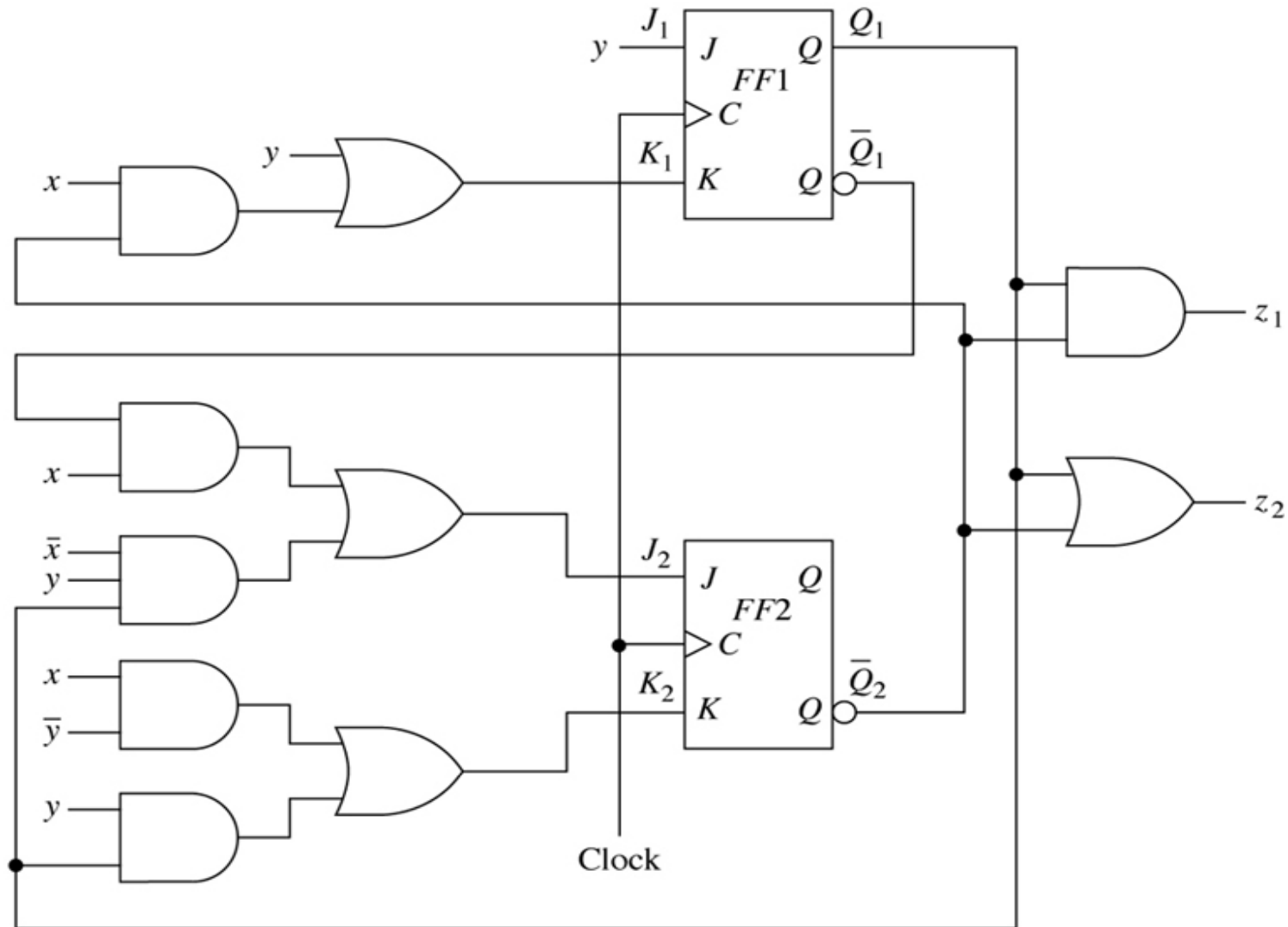


# Timing diagram for Exercise 2 FSM



### Exercise 3

- Draw the state diagram for FSM below. The machine has two inputs  $x$  and  $y$  and two outputs  $z_1$  and  $z_2$ .



# Solution to Exercise 3

